# Multilevel Methods for <br> Uncertainty Quantification of Elliptic PDEs with Random Anisotropic Diffusion 

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# MULTILEVEL METHODS FOR UNCERTAINTY QUANTIFICATION OF ELLIPTIC PDES WITH RANDOM ANISOTROPIC DIFFUSION 

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#### Abstract

We consider elliptic diffusion problems with a random anisotropic diffusion coefficient, where, in a notable direction given by a random vector field, the diffusion strength differs from the diffusion strength perpendicular to this notable direction. The Karhunen-Loève expansion then yields a parametrisation of the random vector field and, therefore, also of the solution of the elliptic diffusion problem. We show that, given regularity of the elliptic diffusion problem, the decay of the Karhunen-Loève expansion entirely determines the regularity of the solution's dependence on the random parameter, also when considering this higher spatial regularity. This result then implies that multilevel collocation and multilevel quadrature methods may be used to lessen the computation complexity when approximating quantities of interest, like the solution's mean or its second moment, while still yielding the expected rates of convergence. Numerical examples in three spatial dimensions are provided to validate the presented theory.


## 1. Introduction

The numerical approximation of quantities of interest, such as expectation, variance, or more general output functionals, of the solution of a diffusion problem with a scalar random diffusion coefficient with multilevel collocation or multilevel quadrature methods has been considered previously, see e.g. $[2,6,10,11,17,20,24,31]$ and the references therein; in this isotropic case, the mixed smoothness required for the use of such multilevel methods has been provided in [7] for uniformly elliptic diffusion coefficients and in [23] for log-normally distributed diffusion coefficients. However, in simulations of certain diffusion phenomena in science and engineering, the diffusion that needs to be modeled may not necessarily be isotropic. One specific application we have in mind here stems from cardiac electrophysiology, where the electrical activation of the human heart is considered. It is known that the fibrous structure of the heart plays a major role when considering the electrical and mechanical properties of the heart. And while the fibres have a complex and generally well-organised structure, see e.g. [28, 29], the exact fibre orientation may vary between individuals and also over time in an individual, for example due to the presence of scaring of the heart.

More generally, we wish to be able to model diffusion in a fibrous media, where fibre direction and diffusion strength in fibre direction are subject to uncertainty. For this setting, the following random anisotropic diffusion coefficient was defined in [21]:

$$
\mathbf{A}(\omega):=a \mathbf{I}+\left(\|\mathbf{V}(\omega)\|_{2}-a\right) \frac{\mathbf{V}(\omega) \mathbf{V}^{\top}(\omega)}{\mathbf{V}^{\top}(\omega) \mathbf{V}(\omega)}
$$

[^0]where $a$ is a given value and $\mathbf{V}$ is a random vector-valued field, over a given spatial domain $D$ and a given probability space $(\Omega, \mathcal{F}, \mathbb{P})$. The fibre direction is hence given by $\mathbf{V} /\|\mathbf{V}\|$ with the diffusion strength in the fibre direction being $\|\mathbf{V}\|$ and the diffusion strength perpendicular to the fibre direction is defined by $a$.

We shall consider the second order diffusion problem with this uncertain diffusion coefficient A given by

$$
\text { for almost every } \omega \in \Omega:\left\{\begin{aligned}
-\operatorname{div}_{\mathbf{x}}\left(\mathbf{A}(\omega) \nabla_{\mathbf{x}} u(\omega)\right)=f & \text { in } D \\
u(\omega)=0 & \text { on } \partial D,
\end{aligned}\right.
$$

with the known function $f$ as a source. The result of this article is then as follows. Having spatial $H^{s}$-regularity of the underlying diffusion problem, given by sufficient smoothness of the right hand $f$ side and the domain $D$, then the random solution $u$ admits analytic regularity with respect to the stochastic parameter also in the $H^{s}(D)$-norm provided that the random vectorvalued field offers enough spatial regularity. This mixed regularity is the essential ingredient in order to apply multilevel collocation or multilevel quadrature methods without deteriorating the rate of convergence, see [17] for instance.

The rest of the article is organised as follows: In Section 2, we provide basic definitions and notation for the functional analytic framework to be able to state and then also reformulate the model problem, by using the Karhunen-Loève expansion of the diffusion describing random vector-valued field $\mathbf{V}$, into its stochastically parametric and spatially weak formulation. Section 3 then deals with the regularity of the solution of the stochastically parametric and spatially weak formulation of the model problem with respect to the stochastic parameter and some given higher spatial regularity in the model problem. We then use the fact that the higher spatial regularity can be kept, when considering the regularity of the solution with respect to the stochastic parameter, to arrive at convergence rates when considering multilevel quadrature, such as multilevel quasiMonte Carlo quadrature, to approximate the solution's mean and second moment. Numerical examples are provided in Section 4 as validation; specifically we use multilevel quasi-Monte Carlo quadrature to approximate the solution's mean and second moment in a setting with three spatial dimensions. Lastly, we give our conclusions in Section 5.

## 2. Problem formulation

2.1. Notation and precursory remarks. For a given Banach space $\mathcal{X}$ and a complete measure space $\mathcal{M}$ with measure $\mu$ the space $L_{\mu}^{p}(\mathcal{M} ; \mathcal{X})$ for $1 \leq p \leq \infty$ denotes the Bochner space, see [22], which contains all equivalence classes of strongly measurable functions $v: \mathcal{M} \rightarrow \mathcal{X}$ with finite norm

$$
\|v\|_{L_{\mu}^{p}(\mathcal{M} ; \mathcal{X})}:= \begin{cases}{\left[\int_{\mathcal{M}}\|v(x)\|_{\mathcal{X}}^{p} \mathrm{~d} \mu(x)\right]^{1 / p},} & p<\infty \\ \underset{x \in \mathcal{M}}{\operatorname{ess} \sup }\|v(x)\|_{\mathcal{X}}, & p=\infty .\end{cases}
$$

A function $v: \mathcal{M} \rightarrow \mathcal{X}$ is strongly measurable if there exists a sequence of countably-valued measurable functions $v_{n}: \mathcal{M} \rightarrow \mathcal{X}$, such that for almost every $m \in \mathcal{M}$ we have $\lim _{n \rightarrow \infty} v_{n}(m)=$ $v(m)$. Note that, for finite measures $\mu$, we also have the usual inclusion $L_{\mu}^{p}(\mathcal{M} ; \mathcal{X}) \supset L_{\mu}^{q}(\mathcal{M} ; \mathcal{X})$ for $1 \leq p<q \leq \infty$.

When $\mathcal{X}$ is a separable Hilbert space and $\mathcal{M}$ is a separable measure space, the Bochner space $L_{\mu}^{2}(\mathcal{M} ; \mathcal{X})$ is also a separable Hilbert space with the inner product

$$
(u, v)_{L_{\mu}^{2}(\mathcal{M} ; \mathcal{X})}:=\int_{\mathcal{M}}(u(x), v(x))_{\mathcal{X}} \mathrm{d} \mu(x)
$$

and is isomorphic to the tensor product space $L_{\mu}^{2}(\mathcal{M}) \otimes \mathcal{X}$, see [25].

Subsequently, we will always equip $\mathbb{R}^{d}$ with the norm $\|\cdot\|_{2}$ induced by the canonical inner product $\langle\cdot, \cdot\rangle$ and $\mathbb{R}^{d \times d}$ with the norm $\|\cdot\|_{F}$ induced by the Frobenius inner product $\langle\cdot, \cdot\rangle_{F}$. Then, for $\mathbf{v}, \mathbf{w} \in \mathbb{R}^{d}$, the Cauchy-Schwartz inequality gives us

$$
\left|\mathbf{v}^{\top} \mathbf{w}\right|=|\langle\mathbf{v}, \mathbf{w}\rangle| \leq\|\mathbf{v}\|_{2}\|\mathbf{w}\|_{2}
$$

where equality holds only if $\mathbf{v}=\mathbf{w}$, and we also have, by straightforward computation, that

$$
\left\|\mathbf{v} \mathbf{w}^{\top}\right\|_{F}=\|\mathbf{v}\|_{2}\|\mathbf{w}\|_{2} .
$$

We also note that to avoid the use of generic but unspecified constants in certain formulas we use $C \lesssim D$ to mean that $C$ can be bounded by a multiple of $D$, independently of parameters which $C$ and $D$ may depend on. Obviously, $C \gtrsim D$ is defined as $D \lesssim C$ and we write $C \gtrsim D$ if $C \lesssim D$ and $C \gtrsim D$. Lastly, note that for the natural numbers $\mathbb{N}$ denotes them including 0 and $\mathbb{N}^{*}$ excluding 0 .
2.2. Model problem. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a separable, complete probability space. Then, we consider the following second order diffusion problem with a random anisotropic diffusion coefficient

$$
\text { for almost every } \omega \in \Omega:\left\{\begin{align*}
-\operatorname{div}_{\mathbf{x}}\left(\mathbf{A}(\omega) \nabla_{\mathbf{x}} u(\omega)\right)=f & \text { in } D  \tag{1}\\
u(\omega)=0 & \text { on } \partial D,
\end{align*}\right.
$$

where $D \subset \mathbb{R}^{d}$ is a Lipschitz domain with $d \geq 1$ and the function $f \in H^{-1}(D)$ describes the known source. The diffusion coefficient is given as the random matrix field $\mathbf{A} \in L_{\mathbb{P}}^{\infty}\left(\Omega ; L^{\infty}\left(D ; \mathbb{R}^{d \times d}\right)\right)$, which satisfies the uniform ellipticity condition

$$
\begin{equation*}
\underline{a} \leq \underset{\mathbf{x} \in D}{\operatorname{ess} \inf } \lambda_{\min }(\mathbf{A}(\mathbf{x}, \omega)) \leq \underset{\mathbf{x} \in D}{\operatorname{ess} \sup } \lambda_{\max }(\mathbf{A}(\mathbf{x}, \omega)) \leq \bar{a} \quad \mathbb{P} \text {-almost surely } \tag{2}
\end{equation*}
$$

for some constants $0<\underline{a} \leq \bar{a}<\infty$ and is almost surely symmetric almost everywhere. Without loss of generality, we assume $\underline{a} \leq 1 \leq \bar{a}$.

We specifically consider diffusion coefficients that are of form

$$
\begin{equation*}
\mathbf{A}(\mathbf{x}, \omega):=a \mathbf{I}+\left(\|\mathbf{V}(\mathbf{x}, \omega)\|_{2}-a\right) \frac{\mathbf{V}(\mathbf{x}, \omega) \mathbf{V}^{\top}(\mathbf{x}, \omega)}{\mathbf{V}^{\top}(\mathbf{x}, \omega) \mathbf{V}(\mathbf{x}, \omega)} \tag{3}
\end{equation*}
$$

where $a \in \mathbb{R}$ is a given positive number and $\mathbf{V} \in L_{\mathbb{P}}^{\infty}\left(\Omega ; L^{\infty}\left(D ; \mathbb{R}^{d}\right)\right)$ is a random vector-valued field. We note that such a field $\mathbf{A}$ accounts for a medium that has homogeneous diffusion strength $a$ perpendicular to $\mathbf{V}$ and has diffusion strength $\|\mathbf{V}(\mathbf{x}, \omega)\|_{2}$ in the direction of $\mathbf{V}$. The randomness of the specific direction and length of $\mathbf{V}$ therefore quantifies uncertainty of this notable direction and its diffusion strength. To guarantee the uniform ellipticity condition (2), we require that

$$
\begin{equation*}
\underline{a} \leq \underset{\mathbf{x} \in D}{\operatorname{essinf}}\|\mathbf{V}(\mathbf{x}, \omega)\| \leq \underset{\mathbf{x} \in D}{\operatorname{ess} \sup }\|\mathbf{V}(\mathbf{x}, \omega)\| \leq \bar{a} \quad \mathbb{P} \text {-almost surely } \tag{4}
\end{equation*}
$$

as well as $\underline{a} \leq a \leq \bar{a}$.
It is assumed that the spatial variable $\mathbf{x}$ and the stochastic parameter $\omega$ of the random field have been separated by the Karhunen-Loève expansion of $\mathbf{V}$, yielding a parametrised expansion

$$
\begin{equation*}
\mathbf{V}(\mathbf{x}, \mathbf{y})=\mathbb{E}[\mathbf{V}](\mathbf{x})+\sum_{k=1}^{\infty} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k} \tag{5}
\end{equation*}
$$

where $\mathbf{y}=\left(y_{k}\right)_{k \in \mathbb{N}^{*}} \in \square:=[-1,1]^{\mathbb{N}^{*}}$ is a sequence of uncorrelated random variables, see e.g. [21]. In the following, we will denote the pushforward of the measure $\mathbb{P}$ onto $\square$ as $\mathbb{P}_{\mathbf{y}}$. Then, we also view $\mathbf{A}(\mathbf{x}, \mathbf{y})$ and $u(\mathbf{x}, \mathbf{y})$ as being parametrised by $\mathbf{y}$ and restate (1) as

$$
\text { for almost every } \mathbf{y} \in \square:\left\{\begin{align*}
-\operatorname{div}_{\mathbf{x}}\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} u(\mathbf{y})\right)=f & \text { in } D  \tag{6}\\
u(\mathbf{y})=0 & \text { on } \partial D .
\end{align*}\right.
$$

We now impose some common assumptions, which make the Karhunen-Loève expansion computationally feasible.

Assumption 2.1. (1) The random variables $\left(y_{k}\right)_{k \in \mathbb{N}^{*}}$ are independent and identically distributed. Moreover, they are uniformly distributed on $[-1,1]$.
(2) The sequence $\boldsymbol{\gamma}=\left(\gamma_{k}\right)_{k \in \mathbb{N}}$, given by

$$
\gamma_{k}:=\left\|\sigma_{k} \boldsymbol{\psi}_{k}\right\|_{L^{\infty}\left(D ; \mathbb{R}^{d}\right)}
$$

is at least in $\ell^{1}(\mathbb{N})$, where we have defined $\boldsymbol{\psi}_{0}:=\mathbb{E}[\mathbf{V}]$ and $\sigma_{0}:=1$.
Lastly, we note that the spatially weak form of (6) is given by

$$
\left\{\begin{array}{l}
\text { Find } u \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; H_{0}^{1}(D)\right) \text { such that }  \tag{7}\\
\quad\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} u(\mathbf{y}), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=(f, v)_{L^{2}\left(D ; \mathbb{R}^{d}\right)} \\
\quad \text { for almost every } \mathbf{y} \in \square \text { and all } v \in H_{0}^{1}(D)
\end{array}\right.
$$

This also entails the well known stability estimate.
Lemma 2.2. There is a unique solution $u \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; H_{0}^{1}(D)\right)$ of (7), which fulfils

$$
\|u(\mathbf{y})\|_{L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; H^{1}(D)\right)} \leq \frac{1}{\underline{a} c_{V}^{2}}\left(\|f\|_{H^{-1}(D)}\right),
$$

where $c_{V}$ is the Poincaré-Friedrichs constant of $H_{0}^{1}(D)$.

## 3. Parametric Regularity

3.1. Precursory remarks. Before we start discussing the regularity of the diffusion coefficient and the solution, we introduce some norms and lemmata, which will then be used in the following subsections.

For the Sobolev spaces $W^{\kappa, p}$ with $\kappa \in \mathbb{N}$ and $1 \leq p \leq \infty$, we introduce the norms given by

$$
\begin{aligned}
\|\mathbf{M}\|_{W^{\kappa, p}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)} & :=\sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}\right\|_{L^{p}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)} \\
& := \begin{cases}\sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left(\int_{D}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}(\mathbf{x})\right\|_{F}^{p} \mathrm{~d} \mathbf{x}\right)^{1 / p}, & p<\infty \\
\sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!} \underset{\mathbf{x} \in D}{\operatorname{ess} \sup }\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}(\mathbf{x})\right\|_{F}, & p=\infty\end{cases}
\end{aligned}
$$

for $\mathbf{M} \in W^{\kappa, p}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)$ with $d_{1}, d_{2} \in \mathbb{N}^{*}$.
For these norms, we have the following lemmata.
Lemma 3.1. Let $\kappa \in \mathbb{N}, 1 \leq p_{1}, p_{2} \leq \infty, d_{1}, d_{2}, d_{3} \in \mathbb{N}^{*}$, and

$$
\mathbf{M}_{1} \in W^{\kappa, p_{1}}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right), \quad \mathbf{M}_{2} \in W^{\kappa, p_{2}}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)
$$

with $q=\left(p_{1}^{-1}+p_{2}^{-1}\right)^{-1} \geq 1$. Then, we have

$$
\left\|\mathbf{M}_{1} \mathbf{M}_{2}\right\|_{W^{\kappa, q}\left(D ; \mathbb{R}^{d_{1} \times d_{3}}\right)} \leq\left\|\mathbf{M}_{1}\right\|_{W^{\kappa, p_{1}}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)}\left\|\mathbf{M}_{2}\right\|_{W^{\kappa, p_{2}}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)}
$$

Proof. Let $\boldsymbol{\alpha}, \boldsymbol{\beta} \in \mathbb{N}^{d}$ be two multi-indices, then we have

$$
\frac{1}{(\alpha+\beta)!}\binom{\alpha+\boldsymbol{\beta}}{\boldsymbol{\beta}}=\frac{1}{(\boldsymbol{\alpha}+\boldsymbol{\beta})!} \frac{(\boldsymbol{\alpha}+\boldsymbol{\beta})!}{\alpha!\boldsymbol{\beta}!}=\frac{1}{\boldsymbol{\alpha}!\boldsymbol{\beta}!} .
$$

We now can calculate

$$
\begin{aligned}
\left\|\mathbf{M}_{1} \mathbf{M}_{2}\right\|_{W^{\kappa, q}\left(D ; \mathbb{R}^{d_{1} \times d_{3}}\right)} & =\sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}}\left[\mathbf{M}_{1} \mathbf{M}_{2}\right]\right\|_{L^{q}\left(D ; \mathbb{R}^{d_{1} \times d_{3}}\right)} \\
& =\sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left\|\sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}} \partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1} \partial_{\mathbf{x}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{M}_{2}\right\|_{L^{q}\left(D ; \mathbb{R}^{d_{1} \times d_{3}}\right)} \\
& \leq \sum_{|\boldsymbol{\alpha}| \leq \kappa} \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}} \frac{1}{\boldsymbol{\alpha}!}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1} \partial_{\mathbf{x}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{M}_{2}\right\|_{L^{q}\left(D ; \mathbb{R}^{d_{1} \times d_{3}}\right)} \\
& \leq \sum_{|\boldsymbol{\alpha}| \leq \kappa} \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}} \frac{1}{\boldsymbol{\alpha}!}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1}\right\|_{L^{p_{1}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)}}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{M}_{2}\right\|_{L^{p_{2}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)}} .
\end{aligned}
$$

By a change of variables, i.e. replacing $\boldsymbol{\alpha}$ with $\boldsymbol{\alpha}+\boldsymbol{\beta}$, and remarking that

$$
\{(\boldsymbol{\alpha}-\boldsymbol{\beta}, \boldsymbol{\beta}):|\boldsymbol{\alpha}| \leq \kappa, \boldsymbol{\beta} \leq \boldsymbol{\alpha}\}=\{(\boldsymbol{\alpha}, \boldsymbol{\beta}):|\boldsymbol{\alpha}|+|\boldsymbol{\beta}| \leq \kappa\}
$$

we find the identity

$$
\begin{aligned}
& \sum_{|\boldsymbol{\alpha}| \leq \kappa} \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}} \frac{1}{\boldsymbol{\alpha}!}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1}\right\|_{L^{p_{1}}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{M}_{2}\right\|_{L^{p_{2}}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)} \\
& \quad=\sum_{|\boldsymbol{\alpha}|+|\boldsymbol{\beta}| \leq \kappa} \frac{1}{(\boldsymbol{\alpha}+\boldsymbol{\beta})!}\binom{\boldsymbol{\alpha}+\boldsymbol{\beta}}{\boldsymbol{\beta}}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1}\right\|_{L^{p_{1}}\left(D ; \mathbb{R}^{\left.d_{1} \times d_{2}\right)}\right.}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}_{2}\right\|_{L^{p_{2}}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)} \\
& \quad=\sum_{|\boldsymbol{\alpha}|+|\boldsymbol{\beta}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!\boldsymbol{\beta}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1}\right\|_{L^{p_{1}}\left(D ; \mathbb{R}^{\left.d_{1} \times d_{2}\right)}\right.}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}_{2}\right\|_{L^{p_{2}}\left(D ; \mathbb{R}^{\left.d_{2} \times d_{3}\right)}\right.} .
\end{aligned}
$$

Consequently, we arrive at the desired estimate:

$$
\begin{aligned}
\left\|\mathbf{M}_{1} \mathbf{M}_{2}\right\|_{W^{\kappa, q}\left(D ; \mathbb{R}^{d_{1} \times d_{3}}\right)} & \leq \sum_{|\boldsymbol{\alpha}|,|\boldsymbol{\beta}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!\boldsymbol{\beta}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1}\right\|_{L^{p_{1}}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}_{2}\right\|_{L^{p_{2}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)}} \\
& \leq \sum_{|\boldsymbol{\beta}| \leq \kappa} \frac{1}{\boldsymbol{\beta}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\beta}} \mathbf{M}_{1}\right\|_{L^{p_{1}}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)} \sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \mathbf{M}_{2}\right\|_{L^{p_{2}}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)} \\
& =\left\|\mathbf{M}_{1}\right\|_{W^{\kappa, p_{1}}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)}\left\|\mathbf{M}_{2}\right\|_{W^{\kappa, p_{2}\left(D ; \mathbb{R}^{d_{2} \times d_{3}}\right)}} .
\end{aligned}
$$

Lemma 3.2. Let $\kappa \in \mathbb{N}, 1 \leq p \leq \infty$, and

$$
\mathbf{v}=\left[v_{i}\right]_{i=1}^{d} \in W^{\kappa, p}\left(D ; \mathbb{R}^{d}\right) .
$$

Then, we have

$$
\left\|\operatorname{div}_{\mathbf{x}} \mathbf{v}\right\|_{W^{\kappa-1, p}(D)} \leq \kappa d\|\mathbf{v}\|_{W^{\kappa, p}\left(D ; \mathbb{R}^{d}\right)} .
$$

Proof. We calculate

$$
\begin{aligned}
\left\|\operatorname{div}_{\mathbf{x}} \mathbf{v}\right\|_{W^{\kappa-1, p}(D)} & =\left\|\sum_{i=1}^{d} \partial_{x_{i}} v_{i}\right\|_{W^{\kappa-1, p}(D)} \leq \sum_{|\boldsymbol{\alpha}| \leq \kappa-1} \frac{1}{\boldsymbol{\alpha}!} \sum_{i=1}^{d}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \partial_{x_{i}} v_{i}\right\|_{L^{p}(D)} \\
& \leq \kappa \sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!} \sum_{i=1}^{d}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} v_{i}\right\|_{L^{p}(D)} \leq \kappa d\|\mathbf{v}\|_{W^{\kappa, p}\left(D ; \mathbb{R}^{d}\right)}
\end{aligned}
$$

Lemma 3.3. Let $\kappa \in \mathbb{N}, 1 \leq p \leq \infty$, and

$$
u \in W^{\kappa, p}(D)
$$

Then, we have

$$
\left\|\nabla_{\mathbf{x}} u\right\|_{W^{\kappa-1, p}\left(D ; \mathbb{R}^{d}\right)} \leq \kappa d\|u\|_{W^{\kappa, p}(D)}
$$

Proof. We calculate

$$
\left.\begin{array}{rl}
\left\|\nabla_{\mathbf{x}} u\right\|_{W^{\kappa-1, p}\left(D ; \mathbb{R}^{d}\right)} & =\sum_{|\boldsymbol{\alpha}| \leq \kappa-1} \frac{1}{\boldsymbol{\alpha}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \nabla_{\mathbf{x}} u\right\|_{L^{p}\left(D ; \mathbb{R}^{d}\right)}=\sum_{|\boldsymbol{\alpha}| \leq \kappa-1} \frac{1}{\boldsymbol{\alpha}!}\| \|_{\partial_{\mathbf{x}}^{\alpha} \partial_{x_{1}} u}^{\vdots} \\
\partial_{\mathbf{x}}^{\boldsymbol{\alpha}} \partial_{x_{d}} u
\end{array}\right] \|_{L^{p}\left(D ; \mathbb{R}^{d}\right)} .
$$

As we will need the Faà di Bruno formula, see [8], we just restate it here for reference:
Remark 3.4. Given $v: \mathbb{R} \rightarrow \mathbb{R}$ and $M: D \rightarrow \mathbb{R}$ (both sufficiently differentiable for the formula to make sense), then

$$
\partial_{\mathbf{x}}^{\boldsymbol{\alpha}}[v \circ M](\mathbf{x})=\sum_{r=1}^{|\boldsymbol{\alpha}|}\left[\mathrm{D}_{x}^{r} v\right](M(\mathbf{x})) \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{|\boldsymbol{\alpha}|} \frac{\left(\partial_{\mathbf{x}}^{\boldsymbol{\beta}_{j}} M(\mathbf{x})\right)^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}}
$$

where $P(\boldsymbol{\alpha}, r)$ is a subset of integer partitions of a multi-index $\boldsymbol{\alpha}$ into $r$ non-vanishing multiindices, given by

$$
\begin{aligned}
P(\boldsymbol{\alpha}, r):=\{ & \left(\left(k_{1}, \boldsymbol{\beta}_{1}\right), \ldots,\left(k_{n}, \boldsymbol{\beta}_{n}\right)\right) \in\left(\mathbb{N} \times \mathbb{N}^{M}\right)^{n}: \sum_{j=1}^{n} k_{j} \boldsymbol{\beta}_{j}=\boldsymbol{\alpha}, \sum_{j=1}^{n} k_{j}=r, \\
& \text { and there exists } 1 \leq s \leq n: k_{j}=0 \text { and } \boldsymbol{\beta}_{j}=\mathbf{0} \text { for all } 1 \leq j \leq n-s, \\
& \left.k_{j}>0 \text { for all } n-s+1 \leq j \leq n \text { and } \mathbf{0} \prec \boldsymbol{\beta}_{n-s+1} \prec \cdots \boldsymbol{\beta}_{n}\right\} .
\end{aligned}
$$

The relation $\boldsymbol{\beta} \prec \boldsymbol{\beta}^{\prime}$ for multi-indices $\boldsymbol{\beta}, \boldsymbol{\beta}^{\prime} \in \mathbb{N}^{M}$ means that either $|\boldsymbol{\beta}|<\left|\boldsymbol{\beta}^{\prime}\right|$ or, when $|\boldsymbol{\beta}|=\left|\boldsymbol{\beta}^{\prime}\right|$, there exists $0 \leq k<m$ such that $\beta_{1}=\beta_{1}^{\prime}, \ldots, \beta_{k}=\beta_{k}^{\prime}$ and $\beta_{k+1}<\beta_{k+1}^{\prime}$.

We also know from [8] that:
Remark 3.5. For $\boldsymbol{\alpha} \in \mathbb{N}^{d}$ with $n=|\boldsymbol{\alpha}|$ and $r \in \mathbb{N}$, we have

$$
\sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{1}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}}=S_{n, r}
$$

where $S_{n, r}$ denotes the Stirling numbers of the second kind, see [1].
Lemma 3.6. Let $\kappa \in \mathbb{N}$ and $M \in W^{\kappa, \infty}(D ; \mathbb{R})$ with $0<\underline{m} \leq 1 \leq \bar{m}<\infty$ such that

$$
\underline{m} \leq \underset{\mathbf{x} \in D}{\operatorname{ess} \operatorname{sinf}}\|M(\mathbf{x})\|_{F} \leq \underset{\mathbf{x} \in D}{\operatorname{esssup}}\|M(\mathbf{x})\|_{F} \leq \bar{m}
$$

as well as $v(x)=x^{-1}$ and $w(x)=\sqrt{x}$. Then, we have

$$
\|v \circ M\|_{W^{\kappa, \infty}(D ; \mathbb{R})} \leq c_{\kappa, d} \frac{1}{\underline{\underline{m}}^{\kappa+1}} \max \left\{1,\|M\|_{W^{\kappa, \infty}(D ; \mathbb{R})}^{\kappa}\right\}
$$

and

$$
\|w \circ M\|_{W^{\kappa, \infty}(D ; \mathbb{R})} \leq c_{\kappa, d} \frac{\sqrt{\bar{m}}}{\underline{m}^{\kappa}} \max \left\{1,\|M\|_{W^{\kappa, \infty}(D ; \mathbb{R})}^{\kappa}\right\}
$$

with

$$
c_{\kappa, d}=1+\sum_{|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|} r!S_{|\boldsymbol{\alpha}|, r} .
$$

Proof. We first remark that the $r$-th derivative of $v$ is given by

$$
\mathrm{D}_{x}^{r} v(x)=(-1)^{r} r!x^{-1-r}=(-1)^{r} r!v(x)^{r+1} .
$$

Next, we employ the Faà di Bruno formula to compute

$$
\begin{aligned}
& \|v \circ M\|_{W^{\kappa, \infty}(D)}=\sum_{|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left\|\partial_{\mathbf{x}}^{\boldsymbol{\alpha}}[v \circ M]\right\|_{L^{\infty}(D)} \\
& \quad=\|v \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!}\left\|\sum_{r=1}^{|\boldsymbol{\alpha}|}\left[\mathrm{D}_{x}^{r} v\right] \circ M \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{|\boldsymbol{\alpha}|} \frac{\left(\partial_{\mathbf{x}}^{\boldsymbol{\beta}_{j}} M\right)^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}}\right\|_{L^{\infty}(D)} \\
& \quad \leq\|v \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \frac{1}{\boldsymbol{\alpha}!} \sum_{r=1}^{|\boldsymbol{\alpha}|}\left\|\left[\mathrm{D}_{x}^{r} v\right] \circ M\right\|_{L^{\infty}(D)} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{|\boldsymbol{\alpha}|} \frac{1}{k_{j}!}\left\|\frac{\partial_{\mathbf{x}}^{\boldsymbol{\beta}_{j}} M}{\boldsymbol{\beta}_{j}!}\right\|_{L^{\infty}(D)}^{k_{j}} \\
& \quad \leq\|v \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\left\|\left[\mathrm{D}_{x}^{r} v\right] \circ M\right\|_{L^{\infty}(D)}\|M\|_{W^{\kappa, \infty}(D ; \mathbb{R})}^{r} \sum_{P(\boldsymbol{\alpha}, r)} \prod_{j=1}^{|\boldsymbol{\alpha}|} \frac{1}{k_{j}!} \\
& \quad \leq\left(\|v \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\left\|\left[\mathrm{D}_{x}^{r} v\right] \circ M\right\|_{L^{\infty}(D)} S_{|\boldsymbol{\alpha}|, r}\right) \max \left\{1,\|M\|_{W^{\kappa, \infty}(D ; \mathbb{R})}^{\kappa}\right\} .
\end{aligned}
$$

Thus, we continue by calculating

$$
\begin{aligned}
\| v & \circ M\left\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\right\|\left[\mathrm{D}_{x}^{r} v\right] \circ M \|_{L^{\infty}(D)} S_{|\boldsymbol{\alpha}|, r} \\
& =\|v \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\left\|(-1)^{r} r!v(M(\mathbf{x}))^{r+1}\right\|_{L^{\infty}(D)} S_{|\boldsymbol{\alpha}|, r} \\
& \leq\|v \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\|v \circ M\|_{L^{\infty}(D)}^{r+1} r!S_{|\boldsymbol{\alpha}|, r} \\
& \leq \frac{1}{\underline{m}}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|} \frac{1}{\underline{m}^{r+1}} r!S_{|\boldsymbol{\alpha}|, r} \\
& \leq\left(1+\sum_{|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|} r!S_{|\boldsymbol{\alpha}|, r}\right) \frac{1}{\underline{m}^{\kappa+1}} .
\end{aligned}
$$

The calculation for $w$ instead of $v$ is mainly analogous: The $r$-th derivative of $w$ is given by

$$
\mathrm{D}_{x}^{r} w(x)=c_{r} x^{\frac{1}{2}-r}=c_{r} w(x) v(x)^{r},
$$

where $c_{r}:=\prod_{i=0}^{r-1}\left(\frac{1}{2}-i\right)$. As $\left|c_{r}\right| \leq r$ !, we can use

$$
\|w \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\left\|\left[\mathrm{D}_{x}^{r} w\right] \circ M\right\|_{L^{\infty}(D)} S_{|\boldsymbol{\alpha}|, r}
$$

$$
\begin{aligned}
& =\|w \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|} \| c_{r} w(M(\mathbf{x})) v\left(M(\mathbf{x})^{r} \|_{L^{\infty}(D)} S_{|\boldsymbol{\alpha}|, r}\right. \\
& \leq\|w \circ M\|_{L^{\infty}(D)}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|}\|w \circ M\|_{L^{\infty}(D)}\|v \circ M\|_{L^{\infty}(D)}^{r} r!S_{|\boldsymbol{\alpha}|, r} \\
& \leq \sqrt{\bar{m}}+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|} \frac{\sqrt{\bar{m}}}{\underline{m}^{r}} r!S_{|\boldsymbol{\alpha}|, r} \\
& \leq\left(1+\sum_{1 \leq|\boldsymbol{\alpha}| \leq \kappa} \sum_{r=1}^{|\boldsymbol{\alpha}|} r!S_{|\boldsymbol{\alpha}|, r}\right) \frac{\sqrt{\bar{m}}}{\underline{m}^{\kappa}}
\end{aligned}
$$

3.2. Parametric regularity of the diffusion coefficient. For the following, we introduce the shorthand notations

$$
\|\mathbf{M}\|_{\kappa, d_{1} \times d_{2}}:=\|\mathbf{M}\|_{L_{P_{\mathbf{y}}}^{\infty}\left(\square ; W^{\kappa, \infty}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)\right)}
$$

for $\mathbf{M} \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; W^{\kappa, \infty}\left(D ; \mathbb{R}^{d_{1} \times d_{2}}\right)\right)$ with $\kappa \in \mathbb{N}$ and $d_{1}, d_{2} \in \mathbb{N}^{*}$; as well as

$$
\begin{gathered}
\|\cdot\|_{\kappa}:=\|\cdot\| \cdot \|_{\kappa, 1 \times 1}, \\
\|\cdot\|_{\kappa, d_{1}}:=\|\cdot\| \cdot \|_{\kappa, d_{1} \times 1} .
\end{gathered}
$$

We now provide regularity estimates for the different terms that make up the diffusion coefficient, based on the following assumption on the decay of the expansion of $\mathbf{V}$.
Assumption 3.7. We assume that the $\boldsymbol{\psi}_{k}$ are elements of $W^{\kappa, \infty}\left(D ; \mathbb{R}^{d}\right)$ for $a \kappa \in \mathbb{N}$ and that the sequence $\boldsymbol{\gamma}_{\kappa}=\left(\gamma_{\kappa, k}\right)_{k \in \mathbb{N}}$, given by

$$
\gamma_{\kappa, k}:=\left\|\sigma_{k} \boldsymbol{\psi}_{k}\right\|_{W^{\kappa, \infty}\left(D ; \mathbb{R}^{d}\right)}
$$

is at least in $\ell^{1}(\mathbb{N})$. Furthermore, we define

$$
c_{\gamma_{\kappa}}=\max \left\{\left\|\gamma_{\kappa}\right\|_{\ell^{1}(\mathbb{N})}, 1\right\} .
$$

We furthermore assume that the vector field $\mathbf{V}$ is given by a finite rank Karhunen-Loève expansion, i.e.

$$
\mathbf{V}(\mathbf{x}, \mathbf{y})=\mathbb{E}[\mathbf{V}](\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}
$$

where $\square:=[-1,1]^{M}$. We note that the regularity estimates however will not depend on the rank $M$. If necessary, a finite rank can be attained by appropriate truncation.

Lemma 3.8. Let $\mathbf{B}$ be defined as

$$
\mathbf{B}(\mathbf{x}, \mathbf{y}):=\mathbf{V}(\mathbf{x}, \mathbf{y}) \mathbf{V}^{\top}(\mathbf{x}, \mathbf{y})
$$

Then, we have for all $\boldsymbol{\alpha} \in \mathbb{N}^{M}$ that

$$
\left\|\partial_{\mathbf{y}}^{\alpha} \mathbf{B}\right\|_{\kappa, d \times d} \leq 2 c_{\gamma_{\kappa}}^{2} \gamma_{\kappa}^{\alpha} .
$$

Proof. More verbosely, B is given by

$$
\mathbf{B}(\mathbf{x}, \mathbf{y})=\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right)\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right)^{\top}
$$

from which we can derive the first order derivatives, yielding

$$
\begin{align*}
\partial_{y_{i}} \mathbf{B}(\mathbf{x}, \mathbf{y})= & \sigma_{i} \boldsymbol{\psi}_{i}(\mathbf{x})\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right)^{\top} \\
& +\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right) \sigma_{i} \boldsymbol{\psi}_{i}^{\top}(\mathbf{x}) \tag{8}
\end{align*}
$$

and from those also the second order derivatives. They are given by

$$
\begin{equation*}
\partial_{y_{j}} \partial_{y_{i}} \mathbf{B}(\mathbf{x}, \mathbf{y})=\sigma_{i} \boldsymbol{\psi}_{i}(\mathbf{x}) \sigma_{j} \boldsymbol{\psi}_{j}^{\top}(\mathbf{x})+\sigma_{j} \boldsymbol{\psi}_{j}(\mathbf{x}) \sigma_{i} \boldsymbol{\psi}_{i}^{\top}(\mathbf{x}) \tag{9}
\end{equation*}
$$

Since the second order derivatives with respect to $\mathbf{y}$ are constant, all higher order derivatives with respect to $\mathbf{y}$ vanish.

We obviously have

$$
\|\mathbf{B}\|_{\kappa, d \times d} \leq c_{\boldsymbol{\gamma}_{\kappa}}^{2} .
$$

From (8) we can now derive the bound

$$
\left\|\partial_{y_{i}} \mathbf{B}\right\|_{\kappa, d \times d} \leq 2\left\|\sigma_{i} \boldsymbol{\psi}_{i}\right\|_{\kappa, d}\left\|\boldsymbol{\psi}_{0}+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k} y_{k}\right\|_{\kappa, d} \leq 2 \gamma_{\kappa, i} c_{\boldsymbol{\gamma}_{\kappa}}
$$

and (9) leads us to

$$
\left\|\partial_{y_{j}} \partial_{y_{i}} \mathbf{B}\right\|_{\kappa, d \times d} \leq 2\left\|\sigma_{i} \boldsymbol{\psi}_{i}\right\|_{\kappa, d}\left\|\sigma_{j} \boldsymbol{\psi}_{j}\right\|_{\kappa, d} \leq 2 \gamma_{\kappa, i} \gamma_{\kappa, j} .
$$

Therefore, we have

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{B}\right\|_{\kappa, d \times d} \leq \begin{cases}c_{\boldsymbol{\gamma}_{\kappa}}^{2} \gamma_{\kappa}^{\boldsymbol{\alpha}}, & \text { if }|\boldsymbol{\alpha}|=0 \\ 2 c_{\boldsymbol{\gamma}_{\kappa}} \gamma_{\kappa}^{\alpha}, & \text { if }|\boldsymbol{\alpha}|=1 \\ 2 \boldsymbol{\gamma}_{\kappa}^{\alpha}, & \text { if }|\boldsymbol{\alpha}|=2 \\ 0, & \text { if }|\boldsymbol{\alpha}|>2\end{cases}
$$

and are finished since $c_{\gamma_{\kappa}} \geq 1$.
Lemma 3.9. Let us define

$$
\begin{gathered}
C(\mathbf{x}, \mathbf{y}):=\mathbf{V}^{\top}(\mathbf{x}, \mathbf{y}) \mathbf{V}(\mathbf{x}, \mathbf{y}), \\
D(\mathbf{x}, \mathbf{y}):=(C(\mathbf{x}, \mathbf{y}))^{-1}, \\
E(\mathbf{x}, \mathbf{y}):=\sqrt{C(\mathbf{x}, \mathbf{y})} .
\end{gathered}
$$

Then, we know for all $\boldsymbol{\alpha} \in \mathbb{N}^{M}$ that

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} D\right\|_{\kappa} \leq|\boldsymbol{\alpha}|!c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\alpha}}
$$

and

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} E\right\|_{\kappa} \leq|\boldsymbol{\alpha}|!c_{\kappa, d} \frac{\bar{a} c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}}\left(c_{\kappa, d} \frac{2 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\boldsymbol{\alpha}}
$$

Proof. C can be expressed as

$$
C(\mathbf{x}, \mathbf{y})=\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right)^{\top}\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right)
$$

which, by derivation, gives the following expressions for the first order derivatives:

$$
\begin{align*}
\partial_{y_{i}} C(\mathbf{x}, \mathbf{y})= & \sigma_{i} \boldsymbol{\psi}_{i}^{\top}(\mathbf{x})\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right) \\
& +\left(\boldsymbol{\psi}_{0}(\mathbf{x})+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k}(\mathbf{x}) y_{k}\right)^{\top} \sigma_{i} \boldsymbol{\psi}_{i}(\mathbf{x}) . \tag{10}
\end{align*}
$$

Computing the second order derivatives then yields

$$
\begin{equation*}
\partial_{y_{j}} \partial_{y_{i}} C(\mathbf{x}, \mathbf{y})=\sigma_{i} \boldsymbol{\psi}_{i}^{\top}(\mathbf{x}) \sigma_{j} \boldsymbol{\psi}_{j}(\mathbf{x})+\sigma_{j} \boldsymbol{\psi}_{j}^{\top}(\mathbf{x}) \sigma_{i} \boldsymbol{\psi}_{i}(\mathbf{x}) \tag{11}
\end{equation*}
$$

and all higher order derivatives with respect to $\mathbf{y}$ are zero, since the second order derivatives with respect to $\mathbf{y}$ are constant.

We know that

$$
\|C\|_{\kappa} \leq\|\mathbf{V}\|_{\kappa, d}^{2} \leq c_{\gamma_{\kappa}}^{2}
$$

Using (10) yields the bound

$$
\left\|\partial_{y_{i}} C\right\|_{\kappa} \leq 2\left\|\sigma_{i} \boldsymbol{\psi}_{i}\right\|_{\kappa, d}\left\|\boldsymbol{\psi}_{0}+\sum_{k=1}^{M} \sigma_{k} \boldsymbol{\psi}_{k} y_{k}\right\|_{\kappa, d} \leq 2 \gamma_{\kappa, i} c_{\gamma_{\kappa}}
$$

and from (11) we can derive the bound

$$
\left\|\partial_{y_{j}} \partial_{y_{i}} C\right\|_{\kappa} \leq 2\left\|\sigma_{i} \boldsymbol{\psi}_{i}\right\|_{\kappa, d}\left\|\sigma_{j} \boldsymbol{\psi}_{j}\right\|_{\kappa, d} \leq 2 \gamma_{\kappa, i} \gamma_{\kappa, j} .
$$

Thus, we conclude that

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} C\right\|_{\kappa} \leq 2 c_{\gamma_{\kappa}}^{2} \gamma_{\kappa}^{\alpha} .
$$

We also use (4) to arrive at

$$
\underline{a}^{2} \leq \underset{\mathbf{y} \in \square}{\operatorname{ess} \inf } \underset{\mathbf{x} \in D}{\operatorname{ess} \inf }\|V(\mathbf{x}, \mathbf{y})\|_{F}^{2}=\underset{\mathbf{y} \in \square}{\operatorname{ess} \inf } \underset{\mathbf{x} \in D}{\operatorname{ess} \inf }\|C(\mathbf{x}, \mathbf{y})\|_{F}
$$

as well as

$$
\underset{\mathbf{y} \in \square}{\operatorname{ess} \sup } \underset{\mathbf{x} \in D}{\operatorname{ess} \sup }\|C(\mathbf{x}, \mathbf{y})\|_{F}=\underset{\mathbf{y} \in \square}{\operatorname{ess} \sup } \underset{\mathbf{x} \in D}{\operatorname{ess} \sup }\|V(\mathbf{x}, \mathbf{y})\|_{F}^{2} \leq \bar{a}^{2} .
$$

Now, in view of Lemma 3.6, we arrive at

$$
\|D\|_{\kappa} \leq c_{\kappa, d} \frac{c_{\gamma_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}
$$

and

$$
\|E\|_{\kappa} \leq c_{\kappa, d} \frac{\bar{a} c_{\gamma_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}},
$$

as $\|C\| \|_{\kappa} \leq c_{\gamma_{\kappa}}^{2}$ with $c_{\gamma_{\kappa}} \geq \bar{a} \geq 1$.
Because $D=v \circ C$ with $v(x)=x^{-1}$ and $E=w \circ C$ with $w(x)=\sqrt{x}$ are composite functions, we employ the Faà di Bruno formula, see Remark 3.4, to compute their derivatives. We remark that the $r$-th derivative of $v$ is given by

$$
\mathrm{D}_{x}^{r} v(x)=(-1)^{r} r!x^{-1-r}=(-1)^{r} r!v(x)^{r+1}
$$

and the $r$-th derivative of $w$ is given by

$$
\mathrm{D}_{x}^{r} w(x)=c_{r} x^{\frac{1}{2}-r}=c_{r} w(x) v(x)^{r}
$$

where $c_{r}:=\prod_{i=0}^{r-1}\left(\frac{1}{2}-i\right)$. For $n=|\boldsymbol{\alpha}|$, we thus arrive at

$$
\begin{equation*}
\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} D(\mathbf{x}, \mathbf{y})=\sum_{r=1}^{n}(-1)^{r} r!D(\mathbf{x}, \mathbf{y})^{r+1} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{\left(\partial_{\mathbf{y}}^{\boldsymbol{\beta}_{j}} C(\mathbf{x}, \mathbf{y})\right)^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} \tag{12}
\end{equation*}
$$

and

$$
\begin{equation*}
\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} E(\mathbf{x}, \mathbf{y})=\sum_{r=1}^{n} c_{r} E(\mathbf{x}, \mathbf{y}) D(\mathbf{x}, \mathbf{y})^{r} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{\left(\partial_{\mathbf{y}}^{\boldsymbol{\beta}_{j}} C(\mathbf{x}, \mathbf{y})\right)^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} \tag{13}
\end{equation*}
$$

Taking the norm of (12) and (13) leads us to

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} D\right\|_{\kappa} & \leq \sum_{r=1}^{n} r!\|D\|_{\kappa}^{r+1} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}_{j}} C\right\|_{\kappa}^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} \\
& \leq \sum_{r=1}^{n} r!\left(c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\right)^{r+1} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{\left(2 c_{\boldsymbol{\gamma}_{\kappa}}^{2} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\beta}_{j}}\right)^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} \\
& =\boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\alpha}} \sum_{r=1}^{n} r!\left(c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\right)^{r+1}\left(2 c_{\boldsymbol{\gamma}_{\kappa}}^{2}\right)^{r} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{1}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}}
\end{aligned}
$$

and

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} E\right\|_{\kappa} & \leq \sum_{r=1}^{n}\left|c_{r}\right|\|E\|\left\|_{\kappa}\right\| D \|_{\kappa}^{r} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}_{j}} C\right\|_{\kappa}^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} \\
& \leq \sum_{r=1}^{n}\left|c_{r}\right| c_{\kappa, d} \frac{\bar{a} c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}}\left(c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\right)^{r} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{\left(2 c_{\boldsymbol{\gamma}_{\kappa}}^{2} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\beta}_{j}}\right)^{k_{j}}}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} \\
& =\boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\alpha}} \sum_{r=1}^{n}\left|c_{r}\right| c_{\kappa, d} \frac{\bar{a} c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}}\left(c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\right)^{r}\left(2 c_{\boldsymbol{\gamma}_{\kappa}}^{2}\right)^{r} \sum_{P(\boldsymbol{\alpha}, r)} \boldsymbol{\alpha}!\prod_{j=1}^{n} \frac{1}{k_{j}!\left(\boldsymbol{\beta}_{j}!\right)^{k_{j}}} .
\end{aligned}
$$

Observing $\left|c_{r}\right| \leq r$ ! and Remark 3.5, we can obtain

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} D\right\|_{\kappa} & \leq \gamma_{\kappa}^{\boldsymbol{\alpha}} c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}} \sum_{r=1}^{n} r!\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\right)^{r} S_{n, r} \\
& \leq c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\boldsymbol{\alpha}} \sum_{r=1}^{n} r!S_{n, r}
\end{aligned}
$$

and

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\alpha} E\right\|_{\kappa} & \leq \gamma_{\kappa}^{\boldsymbol{\alpha}} c_{\kappa, d} \frac{\bar{a} c_{\gamma_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}} \sum_{r=1}^{n} r!\left(c_{\kappa, d} \frac{2 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\right)^{r} S_{n, r} \\
& \leq c_{\kappa, d} \frac{\bar{a} c_{\gamma_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}}\left(c_{\kappa, d} \frac{2 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\alpha} \sum_{r=1}^{n} r!S_{n, r}
\end{aligned}
$$

Because $\sum_{r=1}^{n} r!S_{n, r}$ equals the $n$-th ordered Bell number, we can bound it, see [3], by

$$
\sum_{r=1}^{n} r!S_{n, r} \leq \frac{n!}{(\log 2)^{n}}
$$

This implies the assertion.
Lemma 3.10. We define $\mathbf{F}$ by

$$
\mathbf{F}(\mathbf{x}, \mathbf{y}):=\frac{\mathbf{V}(\mathbf{x}, \mathbf{y}) \mathbf{V}^{\top}(\mathbf{x}, \mathbf{y})}{\mathbf{V}^{\top}(\mathbf{x}, \mathbf{y}) \mathbf{V}(\mathbf{x}, \mathbf{y})}
$$

Then, we have for all $\boldsymbol{\alpha} \in \mathbb{N}^{M}$ that

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{F}\right\|_{\kappa, d \times d} \leq|\boldsymbol{\alpha}|!c_{\kappa, d} \frac{6 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\boldsymbol{\alpha}} .
$$

Proof. We can equivalently state $\mathbf{F}$ as $\mathbf{F}(\mathbf{x}, \mathbf{y})=D(\mathbf{x}, \mathbf{y}) \mathbf{B}(\mathbf{x}, \mathbf{y})$. Then, by applying the Leibniz rule, we arrive at

$$
\partial_{\mathbf{y}}^{\alpha} \mathbf{F}(\mathbf{x}, \mathbf{y})=\sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left(\partial_{\mathbf{y}}^{\boldsymbol{\beta}} D(\mathbf{x}, \mathbf{y})\right)\left(\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{B}(\mathbf{x}, \mathbf{y})\right)
$$

Taking the norm and using the bounds from Lemma 3.8 and Lemma 3.9 leads us to

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{F}\right\|_{\kappa, d \times d} & \leq \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}} D\right\|_{\kappa}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{B}\right\|_{\kappa, d \times d} \\
& \leq \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\beta}|!c_{\kappa, d} \frac{c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\beta}|} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\beta}} 2 c_{\boldsymbol{\gamma}_{\kappa}}^{2} \gamma_{\kappa}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \\
& \leq c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\alpha}} \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\beta}|!.
\end{aligned}
$$

Lastly, the combinatorial identity

$$
\begin{equation*}
\sum_{\substack{\boldsymbol{\beta} \leq \boldsymbol{\alpha} \\|\boldsymbol{\beta}|=j}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}=\binom{|\boldsymbol{\alpha}|}{j} \tag{14}
\end{equation*}
$$

yields the bound

$$
\sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\beta}|!=\sum_{j=0}^{|\boldsymbol{\alpha}|} j!\sum_{\substack{\boldsymbol{\beta} \leq \boldsymbol{\alpha} \\|\boldsymbol{\beta}|=j}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}=\sum_{j=0}^{|\boldsymbol{\alpha}|} j!\binom{|\boldsymbol{\alpha}|}{j}=|\boldsymbol{\alpha}|!\sum_{k=0}^{|\boldsymbol{\alpha}|} \frac{1}{k!} \leq 3|\boldsymbol{\alpha}|!.
$$

Theorem 3.11. The derivatives of the diffusion matrix $\mathbf{A}$, defined in (3), satisfy

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{A}\right\|_{\kappa, d \times d} \leq(|\boldsymbol{\alpha}|+1)!c_{\kappa, d} \frac{\bar{a} 12 c_{\gamma_{\kappa}}^{4 \kappa+2}}{\underline{a}^{4 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\boldsymbol{\alpha}}
$$

for all $\boldsymbol{\alpha} \in \mathbb{N}^{M}$ with $|\boldsymbol{\alpha}| \geq 1$.
Proof. We can state A as

$$
\mathbf{A}(\mathbf{x}, \mathbf{y})=a \mathbf{I}+E(\mathbf{x}, \mathbf{y}) \mathbf{F}(\mathbf{x}, \mathbf{y})-a \mathbf{F}(\mathbf{x}, \mathbf{y})
$$

which, with the Leibniz rule, yields

$$
\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{A}(\mathbf{x}, \mathbf{y})=\sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left(\partial_{\mathbf{y}}^{\boldsymbol{\beta}} E(\mathbf{x}, \mathbf{y})\right)\left(\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{F}(\mathbf{x}, \mathbf{y})\right)-a \partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{F}(\mathbf{x}, \mathbf{y})
$$

Then, by taking the norm and inserting the bounds from Lemma 3.9 and Lemma 3.10, we arrive at

$$
\begin{aligned}
& \left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{A}\right\|_{\kappa, d \times d} \leq \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}} E\right\|_{\kappa}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{F}\right\|_{\kappa, d \times d}+\bar{a}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{F}\right\|_{\kappa, d \times d} \\
& \leq \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\beta}|!c_{\kappa, d} \frac{\bar{a} c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa}}{\underline{a}^{2 \kappa}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\beta}|} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\beta}} \\
& |\boldsymbol{\alpha}-\boldsymbol{\beta}|!c_{\kappa, d} \frac{6 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}-\boldsymbol{\beta}|} \boldsymbol{\gamma}_{\kappa}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \\
& +\bar{a}|\boldsymbol{\alpha}|!c_{\kappa, d} \frac{6 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\gamma_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\boldsymbol{\alpha}} \\
& \leq c_{\kappa, d}^{2} \frac{\bar{a} 6 c_{\boldsymbol{\gamma}_{\kappa}}^{4 \kappa+2}}{\underline{a}^{4 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\boldsymbol{\alpha}} \sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\beta}|!|\boldsymbol{\alpha}-\boldsymbol{\beta}|! \\
& +c_{\kappa, d} \frac{\bar{a} 6 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2}}\left(c_{\kappa, d} \frac{2 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2}\right)^{|\boldsymbol{\alpha}|} \gamma_{\kappa}^{\alpha}|\boldsymbol{\alpha}|!.
\end{aligned}
$$

Finally, the combinatorial identity (14) yields, see e.g. [19],

$$
\sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\beta}|!|\boldsymbol{\alpha}-\boldsymbol{\beta}|!=(|\boldsymbol{\alpha}|+1)!
$$

We now define the modified sequence $\boldsymbol{\mu}_{\kappa}=\left(\mu_{\kappa, k}\right)_{k \in \mathbb{N}}$ as

$$
\mu_{\kappa, k}:=c_{\kappa, d} \frac{4 c_{\boldsymbol{\gamma}_{\kappa}}^{2 \kappa+2}}{\underline{a}^{2 \kappa+2} \log 2} \gamma_{\kappa, k}
$$

and also

$$
c_{\kappa, \mathbf{A}}:=c_{\kappa, d}^{2} \frac{\bar{a} 12 c_{\gamma_{\kappa}}^{4 \kappa+2}}{\underline{a}^{4 \kappa+2}} ;
$$

thus, we have

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} \mathbf{A}\right\|_{\kappa, d \times d} \leq|\boldsymbol{\alpha}|!c_{\kappa, \mathbf{A}} \boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} .
$$

Note that the additional factor of 2 in $\mu_{k}$ removes the factor $|\boldsymbol{\alpha}|+1$ from the factorial expression, since we know that $2^{|\boldsymbol{\alpha}|} \geq|\boldsymbol{\alpha}|+1$.
3.3. Parametric regularity of the solution. For this subsection, we require an elliptic regularity result, which we state as an assumption:

Assumption 3.12. For almost any $\mathbf{y}$, the problem of solving

$$
\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} u, \nabla_{x} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=(h, v)_{L^{2}(D)}
$$

for any $h \in H^{\kappa-1}(D)$ has a unique solution $u \in H_{0}^{1}(D)$, which also lies in $H^{\kappa+1}(D)$, with

$$
\|u\|_{H^{\kappa+1}(D)} \leq C_{\kappa, e r}\|h\|_{H^{\kappa-1}(D)},
$$

where $C_{\kappa, \text { er }}$ only depends on $D$ and $\mathbf{A}$.
Remark 3.13. Note that for $\kappa=0$ this reduces to the stability estimate. We will therefore only consider $\kappa \geq 1$; the case for $\kappa=0$ may be found in [21]. Such an elliptic regularity estimate for example is known for $\kappa \geq 1$, when the domain's boundary is of class $C^{\kappa, 1}$ and $\mathbf{A} \in$ $L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; C^{\kappa-1,1}\left(\bar{D} ; \mathbb{R}^{d \times d}\right)\right)$, see $[13$, Theorem 2.5.1.1]. The elliptic regularity estimate is also known
to hold for $\kappa=1$, when the domain is convex and bounded and $\mathbf{A} \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; C^{0,1}\left(\bar{D} ; \mathbb{R}^{d \times d}\right)\right)$, see [13, Theorem 3.2.1.2].

The assumption directly implies the following result.
Lemma 3.14. There is a unique solution $u \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; H_{0}^{1}(D)\right)$ of (7), which fulfils $u(\mathbf{y}) \in$ $H^{k+1}(D)$ for almost every $\mathbf{y} \in \square$, with

$$
\|u(\mathbf{y})\|_{H^{k+1}(D)} \leq C_{\kappa, e r}\|f\|_{H^{\kappa-1}(D)}
$$

However, by also leveraging the higher spatial regularity in the Karhunen-Loève expansion of the random vector-valued field, we can show that the solution $u$ admits analytic regularity with respect to the stochastic parameter $\mathbf{y}$ also in the $H^{\kappa+1}(D)$-norm. This mixed regularity is then the essential ingredient when applying multilevel methods.

Theorem 3.15. For almost every $\mathbf{y} \in \square$, the derivatives of the solution $u(\mathbf{y})$ of (7) satisfy

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{k+1}(D)} \leq|\boldsymbol{\alpha}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}}\left(\max \left\{2,2 C_{\kappa, e r} \kappa^{2} d^{2} c_{\kappa, \mathbf{A}}, C_{\kappa, e r}\|f\|_{H^{\kappa-1}(D)}\right\}\right)^{|\boldsymbol{\alpha}|+1}
$$

Proof. By differentiation of the variational formulation (7) with respect to $\mathbf{y}$ we arrive, for arbitrary $v \in H_{0}^{1}(D)$, at

$$
\left(\partial_{\mathbf{y}}^{\boldsymbol{\alpha}}\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} u(\mathbf{y})\right), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=0
$$

Applying the Leibniz rule on the left-hand side yields

$$
\left(\sum_{\boldsymbol{\beta} \leq \boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}} \partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{A}(\mathbf{y}) \partial_{\mathbf{y}}^{\boldsymbol{\beta}} \nabla_{\mathbf{x}} u(\mathbf{y}), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=0 .
$$

Then, by rearranging and using the linearity of the gradient, we find

$$
\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y}), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=-\left(\sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}} \partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y}), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}
$$

Using Green's identity, we can then write

$$
\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y}), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=\left(\sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}} \operatorname{div}_{\mathbf{x}}\left(\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right), v\right)_{L^{2}(D ; \mathbb{R})}
$$

Thus, we arrive at

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} & \leq C_{\kappa, e r} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}\left\|\operatorname{div}_{\mathbf{x}}\left(\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right)\right\|_{H^{\kappa-1}(D)} \\
& \leq C_{\kappa, e r} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}} \kappa d\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right\|_{H^{\kappa}\left(D ; \mathbb{R}^{d}\right)} \\
& \leq C_{\kappa, e r} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}} \kappa d\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}-\boldsymbol{\beta}} \mathbf{A}\right\|_{\kappa, d \times d}\left\|\nabla_{\mathbf{x}} \partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right\|_{H^{\kappa}\left(D ; \mathbb{R}^{d}\right)} \\
& \leq C_{\kappa, e r} \kappa^{2} d^{2} c_{\kappa, \mathbf{A}} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\alpha}-\boldsymbol{\beta}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}-\boldsymbol{\beta}}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D ; \mathbb{R})},
\end{aligned}
$$

from which we derive

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} \leq \frac{c}{2} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\alpha}-\boldsymbol{\beta}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}-\boldsymbol{\beta}}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)}
$$

where

$$
c:=\max \left\{2,2 C_{\kappa, e r} \kappa^{2} d^{2} c_{\kappa, \mathbf{A}}, C_{\kappa, e r}\|f\|_{H^{\kappa-1}(D)}\right\} .
$$

We note that, by definition of $c$, we have $c \geq 2$ and furthermore, because of Lemma 3.14, we also have that $\|u(\mathbf{y})\|_{H^{1}(D)} \leq c$, which means that the assertion is true for $|\boldsymbol{\alpha}|=0$. Thus, we can use an induction over $|\boldsymbol{\alpha}|$ to prove the hypothesis

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} \leq|\boldsymbol{\alpha}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} c^{|\boldsymbol{\alpha}|+1}
$$

for $|\boldsymbol{\alpha}|>0$.
Let the assertions hold for all $\boldsymbol{\alpha}$, which satisfy $|\boldsymbol{\alpha}| \leq n-1$ for some $n \geq 1$. Then, we know for all $\boldsymbol{\alpha}$ with $|\boldsymbol{\alpha}|=n$ that

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} & \leq \frac{c}{2} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\alpha}-\boldsymbol{\beta}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}-\boldsymbol{\beta}}\left\|\partial_{\mathbf{y}}^{\boldsymbol{\beta}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} \\
& \leq \frac{c}{2} \boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} \sum_{\boldsymbol{\beta}<\boldsymbol{\alpha}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\alpha}-\boldsymbol{\beta}|!|\boldsymbol{\beta}|!c^{|\boldsymbol{\beta}|+1} \\
& =\frac{c}{2} \boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} \sum_{j=0}^{n-1} \sum_{\substack{\boldsymbol{\beta}<\boldsymbol{\alpha} \\
|\boldsymbol{\beta}|=j}}\binom{\boldsymbol{\alpha}}{\boldsymbol{\beta}}|\boldsymbol{\alpha}-\boldsymbol{\beta}|!|\boldsymbol{\beta}|!c^{|\boldsymbol{\beta}|+1}
\end{aligned}
$$

Making use of the combinatorial identity (14) yields

$$
\begin{aligned}
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} & \leq \frac{c}{2} \boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} \sum_{j=0}^{n-1}\binom{|\boldsymbol{\alpha}|}{j}(|\boldsymbol{\alpha}|-j)!j!c^{j+1}=\frac{c}{2}|\boldsymbol{\alpha}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} c \sum_{j=0}^{n-1} c^{j} \\
& \leq \frac{c}{2(c-1)}|\boldsymbol{\alpha}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} c^{|\boldsymbol{\alpha}|+1}
\end{aligned}
$$

Now, since $c \geq 2$, we have $c \leq 2(c-1)$ and hence also

$$
\left\|\partial_{\mathbf{y}}^{\boldsymbol{\alpha}} u(\mathbf{y})\right\|_{H^{\kappa+1}(D)} \leq|\boldsymbol{\alpha}|!\boldsymbol{\mu}_{\kappa}^{\boldsymbol{\alpha}} c^{|\boldsymbol{\alpha}|+1}
$$

This completes the proof.
3.4. Numerical quadrature in the parameter. Coming from the solution $u \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; H_{0}^{1}(D)\right)$ of (7), we now wish to know the moments of $u$. In this section, we will therefore consider the approximation of the mean of $u$. We also require that $\kappa \geq 1$.

The mean of $u$ is given by the Bochner integral

$$
\mathbb{E}[u](\mathbf{x})=\int_{\square} u(\mathbf{x}, \mathbf{y}) \mathrm{d} \mathbf{y}
$$

Therefore, we may proceed to approximate it by considering a generic quadrature method $Q_{N}$; that is

$$
\begin{equation*}
\mathbb{E}[u](\mathbf{x}) \approx Q_{N}[u](\mathbf{x}):=\sum_{i=1}^{N} \omega_{i}^{(N)} u\left(\mathbf{x}, \boldsymbol{\xi}_{i}^{(N)}\right) \tag{15}
\end{equation*}
$$

where

$$
\left\{\left(\omega_{i}^{(N)}, \boldsymbol{\xi}_{i}^{(N)}\right)\right\}_{i=1}^{N} \subset \mathbb{R} \times[0,1]^{M}
$$

are the weight and evaluation point pairs. We assume that the quadrature chosen fulfils

$$
\begin{equation*}
\left\|\mathbb{E}[u]-Q_{N}[u]\right\|_{H^{1}(D)} \leq C N^{-r} \tag{16}
\end{equation*}
$$

for some constants $C>0$ and $r>0$.

We will employ the quasi-Monte Carlo quadrature based on the Halton sequence, i.e. $\omega_{i}^{(N)}=$ $1 / N$ and $\boldsymbol{\xi}_{i}^{(N)}=2 \boldsymbol{\chi}_{i}-\mathbf{1}$, where $\chi_{i}$ denotes the $i$-th $M$-dimensional Halton point, cf. [15]. Then, we know that, given that there exists an $\varepsilon>0$ such that $\gamma_{\kappa, k} \leq c k^{-3-\varepsilon}$ holds for some $c>0$, for every $\delta>0$ there exists a constant $C=C(\delta)>0$ such that (16) holds for $r=1-\delta$, see e.g. [19] which is a consequence of [32]. Clearly, other, possibly more sophisticated, quadrature methods may also be considered, for example, other quasi-Monte Carlo quadratures, such as those based on the Sobol sequence or other low-discrepancy sequences as well as their higher-order adaptations, and anisotropic sparse grid quadratures, see e.g. $[9,14,27,30]$.

To approximate the mean of $u$ as in (15), we require the values $u(\mathbf{x}, \mathbf{y})$ for $\mathbf{y}=\boldsymbol{\xi}_{i}$. These values can be approximated by $u_{l}(\mathbf{x}, \mathbf{y})$, where $u_{l}$ is the Galerkin approximation of the spatially weak formulation on a finite dimensional subspace $V_{l}$ of $H_{0}^{1}(D)$; that is, $u_{l}$ is the solution of

$$
\left\{\begin{array}{l}
\text { Find } u_{l} \in L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; V_{l}\right) \text { such that } \\
\quad\left(\mathbf{A}(\mathbf{y}) \nabla_{\mathbf{x}} u_{l}(\mathbf{y}), \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=(f, v)_{L^{2}\left(D ; \mathbb{R}^{d}\right)} \\
\quad \text { for almost every } \mathbf{y} \in \square \text { and all } v \in V_{l} .
\end{array}\right.
$$

We assume that a sequence of $V_{l}$ can be chosen for $l \in \mathbb{N}$ such that there is a constant $K$ with

$$
\begin{equation*}
\left\|u-u_{l}\right\|_{L_{\mathbb{P}_{y}}^{\infty}\left(\square ; H^{1}(D)\right)} \leq K 2^{-\kappa l} . \tag{17}
\end{equation*}
$$

For example, we can consider $V_{l}$ to be the spaces of continuous finite elements of order $\kappa$ coming from a sequence of quasi-uniform meshes $\mathcal{T}_{l}$ using isoparametric elements, where the mesh size behaves like $2^{-l}$. Then, it is known from finite element theory that we have (17) with $K \sim$ $\|u\|_{L_{\mathbb{P}_{\mathbf{y}}}^{\infty}\left(\square ; H^{\kappa+1}(D)\right)}$, see e.g. [4, 5].

The combination of the error estimates (16) and (17) then leads to

$$
\begin{aligned}
\left\|\mathbb{E}[u]-Q_{N}\left[u_{l}\right]\right\|_{H^{1}(D)} & \leq\left\|\mathbb{E}[u]-Q_{N}[u]\right\|_{H^{1}(D)}+\left\|Q_{N}[u]-Q_{N}\left[u_{l}\right]\right\|_{H^{1}(D)} \\
& \leq\left\|\mathbb{E}[u]-Q_{N}[u]\right\|_{H^{1}(D)}+\left\|Q_{N}\left[u-u_{l}\right]\right\|_{H^{1}(D)} \\
& \leq C N^{-r}+K 2^{-\kappa l} .
\end{aligned}
$$

Thus, choosing $N_{l}:=\left\lceil 2^{\kappa l / r}\right\rceil$ finally yields

$$
\left\|\mathbb{E}[u]-Q_{N_{l}}\left[u_{l}\right]\right\|_{H^{1}(D)} \leq(C+K) 2^{-\kappa l}
$$

In contrast, the mixed regularity, shown before in Theorem 3.15, allows us to consider a multilevel adaptation, which may be given as

$$
\mathbb{E}[u] \approx Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right]:=\sum_{k=0}^{l} \Delta Q_{k}\left[u_{l-k}\right]
$$

where

$$
\Delta Q_{0}:=Q_{N_{0}} \quad \text { and } \quad \Delta Q_{k}:=Q_{N_{k}}-Q_{N_{k-1}}
$$

Indeed, this is the sparse grid combination technique as introduced in [12], see also [11, 17]. It thus follows that

$$
\left\|\mathbb{E}[u]-Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right]\right\|_{H^{1}(D)} \lesssim l 2^{-\kappa l} .
$$

For complexity considerations, we shall consider a quadrature that is nested, i.e. we may set $\boldsymbol{\xi}_{i}=\boldsymbol{\xi}_{i}^{(N)}$ as it does not depend on $N$. Then, we note that $Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right]$ may explicitly be stated as

$$
Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right](\mathbf{x})=\sum_{i=1}^{N_{0}} \omega_{i}^{\left(N_{0}\right)} u_{l}\left(\mathbf{x}, \boldsymbol{\xi}_{i}\right)
$$

$$
+\sum_{k=1}^{l}\left(\sum_{i=1}^{N_{k-1}}\left(\omega_{i}^{\left(N_{k}\right)}-\omega_{i}^{\left(N_{k-1}\right)}\right) u_{l-k}\left(\mathbf{x}, \boldsymbol{\xi}_{i}\right)+\sum_{i=N_{k-1}+1}^{N_{k}} \omega_{i}^{\left(N_{k}\right)} u_{l-k}\left(\mathbf{x}, \boldsymbol{\xi}_{i}\right)\right)
$$

Computing $Q_{N_{l}}\left[u_{l}\right]$ requires thus the values $u_{l, i}(\mathbf{x}):=u\left(\mathbf{x}, \boldsymbol{\xi}_{i}\right)$, which can be derived by solving

$$
\left\{\begin{array}{l}
\text { Find } u_{l, i} \in V_{l} \text { such that } \\
\quad\left(\mathbf{A}\left(\boldsymbol{\xi}_{i}\right) \nabla_{\mathbf{x}} u_{l, i}, \nabla_{\mathbf{x}} v\right)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}=(f, v)_{L^{2}\left(D ; \mathbb{R}^{d}\right)}
\end{array} \quad \text { for all } v \in V_{l} .\right.
$$

Generally, when considering a sequence of finite element spaces $V_{l}$ as described above, the number of degrees of freedom behaves like $\mathcal{O}\left(2^{l d}\right)$ and computing one $u_{l, i}$ using state of the art methods will have a complexity that is $\mathcal{O}\left(2^{l d}\right)$. As this has to be done $N_{l}$ times for the calculation of $Q_{N_{l}}\left[u_{l}\right]$, a complexity scaling is obtained that is $\mathcal{O}\left(2^{l(\kappa / r+d)}\right)$. Therefore, for the computation of the multilevel quadrature $Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right]$, we arrive at an over-all complexity of

$$
\sum_{k=0}^{l} \sum_{i=1}^{N_{k}} \mathcal{O}\left(2^{(l-k) d}\right)=\sum_{k=0}^{l} \mathcal{O}\left(2^{k \kappa / r} 2^{(l-k) d}\right)= \begin{cases}\mathcal{O}\left(2^{l \kappa / r}\right) & \text { for } d<\kappa / r \\ \mathcal{O}\left(l 2^{l \max \{\kappa / r, d\}}\right) & \text { for } d=\kappa / r \\ \mathcal{O}\left(2^{l d}\right) & \text { for } d>\kappa / r\end{cases}
$$

We mention that also non-nested quadrature formulae can be used but lead to a somewhat larger constant in the complexity estimate, see [11] for the details.

Remark 3.16. If we redefine the $N_{l}$ as $N_{l}:=\left\lceil l^{(1+\varepsilon) / r} 2^{\kappa l / r}\right\rceil$ for an $\varepsilon>0$, then we have

$$
\left\|\mathbb{E}[u]-Q_{N_{l}}[u]\right\|_{H^{1}(D)} \leq C\left(l^{(1+\varepsilon) / r} 2^{\kappa l / r}\right)^{-r}=C l^{-(1+\varepsilon)} 2^{-\kappa l}
$$

and, as proposed in [2], we arrive at

$$
\left\|\mathbb{E}[u]-Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right]\right\|_{H^{1}(D)} \lesssim 2^{-\kappa l} .
$$

So, the logarithmic factor, which shows up in the convergence rate, can be removed by increasing the quadrature accuracy slightly faster. Note that this modification increases the hidden constant with a dependance on $\varepsilon$.

Remark 3.17. In the particular situation of a standard quasi-Monte Carlo method, we can consider $\delta^{\prime}$ such that $\delta>\delta^{\prime}>0$. Then, the quadrature error satisfies the estimate

$$
\left\|\mathbb{E}[u]-Q_{N_{l}}[u]\right\|_{H^{1}(D)} \leq C_{\delta^{\prime}} N_{l}^{\delta^{\prime}-1}=C_{\delta^{\prime}} 2^{-\kappa l} 2^{-\kappa l\left(\delta-\delta^{\prime}\right) /(1-\delta)}
$$

With a similar argument as in [2], it follows that

$$
\left\|\mathbb{E}[u]-Q_{l}^{\mathrm{ML}}\left[u_{0}, \ldots, u_{l}\right]\right\|_{H^{1}(D)} \lesssim 2^{-\kappa l}
$$

That is, the logarithmic factor, which shows up in the convergence rate, is removed at the cost of replacing the constant $C_{\delta}$ with $C_{\delta^{\prime}}$ and adds a constant with a dependance on $\delta^{\prime}$ yielding an increased hidden constant.

While we have exclusively considered the case of the mean of the solution $u$ here, we do note that analogous statements may also be shown for example for the higher-order moments, see [17] for instance.

## 4. Numerical Results

We will now consider two examples of the model problem (1) with a diffusion coefficient of form (3) using the unit cube $D:=(0,1)^{3}$ as the domain of computations. Therefore, in view of $H^{2}$-regularity of the spatial problem under consideration, we are only considering the situation with $\kappa=1$. In both examples, we set the global strength $a$ to $a:=0.12$ and choose the right hand side $f \equiv 1$. For convenience, we define

$$
s_{j}\left(\mathbf{x}, \mathbf{x}^{\prime}\right):=16 \cdot x_{j}\left(1-x_{j}\right) \cdot x_{j}^{\prime}\left(1-x_{j}^{\prime}\right) .
$$

Example 1. In this first example, we choose the description of $\mathbf{V}$ to be defined by

$$
\mathbb{E}[\mathbf{V}](\mathbf{x}):=\left[\begin{array}{lll}
1 & 0 & 0
\end{array}\right]^{\top}
$$

and

$$
\operatorname{Cov}[\mathbf{V}]\left(\mathbf{x}, \mathbf{x}^{\prime}\right):=\frac{1}{100} \exp \left(-\frac{\left\|\mathbf{x}-\mathbf{x}^{\prime}\right\|_{2}^{2}}{50}\right)\left[\begin{array}{ccc}
1 & 0 & 0 \\
0 & 9 s_{2}\left(\mathbf{x}, \mathbf{x}^{\prime}\right) & 0 \\
0 & 0 & 9 s_{3}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)
\end{array}\right]
$$

We note that for $j \in\{2,3\}$ the covariance in the normal direction on the parts of the boundary with $x_{j} \in\{0,1\}$ is suppressed.

Example 2. For this second example we choose the description of $\mathbf{V}$ to be defined by

$$
\mathbb{E}[\mathbf{V}](\mathbf{x}):=\left[\begin{array}{c}
\cos \left(\left(x_{3}-0.5\right) \frac{\pi}{3}\right) \\
\sin \left(\left(x_{3}-0.5\right) \frac{\pi}{3}\right) \\
0
\end{array}\right]
$$

and

$$
\mathbb{C o v}[\mathbf{V}]\left(\mathbf{x}, \mathbf{x}^{\prime}\right):=\frac{9}{100} \exp \left(-\frac{\left\|\mathbf{x}-\mathbf{x}^{\prime}\right\|_{2}^{2}}{50}\right)\left[\begin{array}{ccc}
s_{1}\left(\mathbf{x}, \mathbf{x}^{\prime}\right) & 0 & 0 \\
0 & s_{2}\left(\mathbf{x}, \mathbf{x}^{\prime}\right) & 0 \\
0 & 0 & s_{3}\left(\mathbf{x}, \mathbf{x}^{\prime}\right)
\end{array}\right] .
$$

Here, the covariance in the normal direction on all of the boundary is suppressed.
The numerical implementation is performed with aid of the problem-solving environment DOLFIN [26], which is a part of the FEniCS Project [26]. The Karhunen-Loève expansion of the vector field $\mathbf{V}$ is computed by the pivoted Cholesky decomposition, see $[16,18]$ for the details. For the finite element discretisation, we employ the sequence of nested triangulations $\mathcal{T}_{l}$, yielded by successive uniform refinement, i.e. cutting each tetrahedron into 8 tetrahedra. The base triangulation $\mathcal{T}_{0}$ consists of $6 \cdot 2^{3}=48$ tetrahedra. Then, we use interpolation with continuous element-wise linear functions and the truncated pivoted Cholesky decomposition for the Karhunen-Loève expansion approximation and continuous element-wise linear functions in space. The truncation criterion for the pivoted Cholesky decomposition is that the relative trace error is smaller than $10^{-4} \cdot 4^{-l}$.

Since the exact solutions of the examples are unknown, the errors will have to be estimated. Therefore, in this section, we will estimate the errors for the levels 0 to 5 by substituting the exact solution with the approximate solution computed on the level 6 triangulation $\mathcal{T}_{6}$ using the quasi-Monte Carlo quadrature based on Halton points with $10^{4}$ samples.

For every level, we also define the number of samples used by the quasi-Monte Carlo method based on Halton points (QMC); we choose

$$
N_{l}:=\left\lceil 2^{l /(1-\delta)} \cdot 10\right\rceil
$$

with $\delta:=0.2$; see Table 1 for the resulting values of $N_{l}$. This then also implies the amount of samples used on the different levels when using the multilevel quasi-Monte Carlo method based

| $l$ | 0 | 1 | 2 | 3 | 4 | 5 |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: |
| $N_{l}$ | 10 | 24 | 57 | 135 | 320 | 762 |
| $M_{1}$ | 17 | 26 | 30 | 36 | 44 | 52 |
| $M_{2}$ | 14 | 26 | 30 | 36 | 43 | 52 |

Table 1. The number of samples for the first six levels and the respective parameter dimensions.
on Halton points (MLQMC). Based on these choices, we expect to see an asymptotic rate of convergence of $2^{-l}$ in the $H^{1}$-norm for the mean and in the $W^{1,1}$-norm for the variance.

Figures 1 and 2 show the estimated errors of the solution's first moment on the left hand side and of the solution's second moment on the right hand side, each versus the discretisation level for the QMC and MLQMC quadrature for the two different examples. As expected, the QMC quadrature methods achieves the predicted rate of convergence in both examples, and this rate of convergence also carries over to its multilevel adaptation (MLQMC).


Figure 1. Example 1. $H^{1}$-error in the $1^{\text {st }}$ moment (left) and $W^{1,1}$-error in the $2^{\text {nd }}$ moment (right).


Figure 2. Example 2. $H^{1}$-error in the $1^{\text {st }}$ moment (left) and $W^{1,1}$-error in the $2^{\text {nd }}$ moment (right).

## 5. Conclusion

In this article, we have considered the second order diffusion problem

$$
\text { for almost every } \omega \in \Omega:\left\{\begin{aligned}
-\operatorname{div}_{\mathbf{x}}\left(\mathbf{A}(\omega) \nabla_{\mathbf{x}} u(\omega)\right)=f & \text { in } D, \\
u(\omega)=0 & \text { on } \partial D,
\end{aligned}\right.
$$

with the uncertain diffusion coefficent given by

$$
\mathbf{A}(\omega):=a \mathbf{I}+\left(\|\mathbf{V}(\omega)\|_{2}-a\right) \frac{\mathbf{V}(\omega) \mathbf{V}^{\boldsymbol{\top}}(\omega)}{\mathbf{V}^{\top}(\omega) \mathbf{V}(\omega)}
$$

This models anisotropic diffusion, where the diffusion strength in the direction given by $\mathbf{V} /\|\mathbf{V}\|$ is $\|\mathbf{V}\|$ and perpendicular to it is $a$, which can be used to model both diffusion in media that consist of thin fibres or thin sheets.

After having restated the problem in a parametric form by considering the Karhunen-Loève expansion of the random vector field $\mathbf{V}$, we have shown that, given regularity of the elliptic diffusion problem, the decay of the Karhunen-Loève expansion of $\mathbf{V}$ entirely determines the regularity of the solution's dependence on the random parameter, also when considering this higher regularity in the spatial domain.

We then leverage this result to reduce the complexity of the approximation of the solution's mean, by using the multilevel quasi-Monte Carlo method instead of the quasi-Monte Carlo method, while still retaining the same error rate. Indeed, while the QMC method yields a scheme, where the uncertainty added increases the complexity, this is not the case, when considering two or more spatial dimensions and the MLQMC method. That is, given elliptic regularity and up to a constant in the complexity, adding uncertainty comes for free. The numerical experiments corroborate these theoretical findings.

While we considered the use of QMC and its multilevel adaptation, one can clearly also consider other quadrature methods, such as the anisotropic sparse grid quadrature, and then reduce the complexity by passing to their multilevel adaptations. Likewise, multilevel collocation is also applicable.

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